# Error Bounds for Lagrange Interpolation 

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In this paper we study the quantities

$$
\begin{aligned}
L_{m, k}(\Delta, x) & =\sup _{\left\|f^{(m)}\right\| \leq 1}\left|f^{(k)}(x)-I_{m}^{(k)} \mathrm{t}, \Delta(f, x)\right| \\
L_{m, k}(\Delta) & =\sup _{x \in\{a, b \mid} L_{m \cdot k}(\Delta, x)
\end{aligned}
$$

which define error bounds for the approximation of functions $f \in W_{\mathrm{x}}^{\prime \prime \prime}[a, b]$ by the interpolating Lagrange polynomials $l_{m-1,\lrcorner}(f)$ of degree $m-1$, consiructed on the given mesh of interpolating nodes

$$
\Delta=\Delta_{m}=\left\{a \leq t_{1}<\cdots<t_{m} \leq b\right\} .
$$

Set

$$
\omega_{\perp}(x)=\prod_{i=1}^{m}\left(x-t_{i}\right) .
$$

It is clear that

$$
L_{m, k}(\Delta, x) \geq \frac{1}{m!}\left|\omega_{\lrcorner}^{(k)}(x)\right|, \quad L_{m, k}(\Delta) \geq \frac{1}{m!}\left\|\omega_{د}^{(k)}(\cdot)\right\|
$$

Our main result is
Theorem 1. For all $m$ and $k(0 \leq k \leq m-1)$, and for any mesh $\Delta$ of the interpolating nodes $\left\{t_{i}\right\}_{1}^{m}$

$$
L_{m, k}(\Delta)=\frac{1}{m!}\left\|\omega_{\lrcorner}^{(h)}(\cdot)\right\| .
$$

## 1. Introiduction

In this paper we study the quantities

$$
\begin{align*}
L_{m, k}(\Delta, x) & =\sup _{\left\|f^{(m)}\right\|_{\leq 1} \leq 1}\left|f^{(k)}(x)-l_{m-1, \Delta}^{(k)}(f, x)\right|  \tag{1.1}\\
L_{m, k}(\Delta) & =\sup _{x \in[a, b]} L_{m, k}(\Delta, x)
\end{align*}
$$

which define crror bounds for the approximation of functions $f \in W_{x}^{m}[a, b]$ by the interpolating Lagrange polynomials $l_{m-1 .\lrcorner}(f)$ of degree $m-1$, constructed on the given mesh of interpolating nodes

$$
\Delta=\Delta_{m}=\left\{a \leq t_{1}<\cdots<t_{m} \leq b\right\}
$$

Set

$$
\omega_{د}(x)=\prod_{i=1}^{m}\left(x-t_{i}\right)
$$

It is clear that

$$
L_{m, k}(\Delta, x) \geq \frac{1}{m!}\left|\omega_{\lrcorner}^{(k)}(x)\right|, \quad L_{m, k}(\Delta) \geq \frac{1}{m!}\left\|\omega_{\lrcorner}^{(k)}(\cdot)\right\|
$$

Our main result is
Theorem 1. For all $m$ and $k(0 \leq k \leq m-1)$, and for any mesh $\Delta$ of the interpolating nodes $\left\{t_{i}\right\}_{1}^{m}$

$$
\begin{equation*}
L_{m, k}(\Delta)=\frac{1}{m!}\left\|\omega_{د}^{(k)}(\cdot)\right\| \tag{1.2}
\end{equation*}
$$

This theorem is an immediate consequence of the two following statements concerning the value of the point-wise deviation $L_{m, k}(\Delta, x)$. Their formulations include two subsets of the interval $[a, b]$

$$
\begin{array}{ll}
I_{m, k}(\Delta)=\bigcup_{j=0}^{m-k}\left[\alpha_{j}, \beta_{j}\right], & J_{m, k}(\Delta)=\bigcup_{j=1}^{m-k-1}\left(\beta_{j}, \alpha_{j+1}\right) \\
I_{m, k}(\Delta) \cap J_{m, k}(\Delta)=\varnothing, & I_{m, k}(\Delta) \cup J_{m, k}(\Delta)=[a, b]
\end{array}
$$

which will be specified later.

Theorem A. For all $m$ and $k$, and for any mesh $\Delta$

$$
L_{m, k}(\Delta, x)=\frac{1}{m!}\left|\omega_{\lrcorner}^{(k)}(x)\right|, \quad x \in I_{m, k}(\Delta)
$$

Theorem 2. For all $m$ and $k$, and for any mesh $\Delta$ the function $L_{m, k}(\Delta, x)$ has on each interval $\left(\beta_{j}, \alpha_{j+1}\right) \subset J_{m, k}(\Delta)$ at most one extremum, which in this case is the minimum; thus,

$$
\begin{align*}
L_{m, k}(\Delta, x) & <\max \left\{\frac{1}{m!}\left|\omega_{\lrcorner}^{(k)}\left(\beta_{j}\right)\right|, \frac{1}{m!}\left|\omega_{\lrcorner}^{(k)}\left(\alpha_{j+1}\right)\right|\right\} \\
x & \in\left(\beta_{j}, \alpha_{j+1}\right) \subset J_{m, k}(\Delta) \tag{1.3}
\end{align*}
$$

Theorem A was established by H. Kallioniemi [2]. In [3] he made a conjecture that Theorem 2 is valid and gave some conditions on the mesh $\Delta$, providing equality (1.2).

In [6], we proved Theorem 2 for $k=m-1$. If $k=0$, then $J_{m, k}(\Delta)=\varnothing$. In this paper we give a proof of Theorem 2 for arbitrary $k, 1 \leq k \leq m-2$.

The idea of the proof follows that of V. A. Markov [5, p. 88]. Theorems $A$ and 2 are similar to his results concerning the value

$$
\begin{equation*}
N_{m, k}(x)=\sup _{\left\|p_{m-1}\right\| \leq 1}\left|p_{m-1}^{(k)}(x)\right| \tag{1.4}
\end{equation*}
$$

which defines the norm of the functional of the $k$ th derivative at the point $x \in[a, b]$ on the class of algebraic polynomials of degree $m-1$. (See [1] for a condensed original proof of V. A. Markov's inequality.)

Along with problems (1.1)-(1.2) it is natural to consider the problem of finding optimal formulas for the Lagrange interpolation and calculating the value

$$
L_{m, k}=\inf _{\Delta \subset[a, b]} L_{m, k}(\Delta)
$$

Theorem 1 reduces this problem to a minimization problem on the class of polynomials.

Corollary. For all $m$ and $k(0 \leq k \leq m-1)$

$$
L_{m, k}=\inf _{\Delta \subset[a, b]} \frac{1}{m!}\left\|\omega_{د}^{(k)}(\cdot)\right\|
$$

Characterization of an extremal polynomial requires special considerations. Here, without going into details, we mention the papers $[3,4,6]$, where the cases $k=0,1$, and $k \geq[m / 2]$ were considered.

## 2. Preiliminaries

For

$$
\Delta=\Delta_{m}=\left\{a \leq t_{1}<\cdots<t_{m} \leq b\right\}
$$

set

$$
\begin{array}{rlr}
\omega(x) & =\omega_{\lrcorner}(x)=\prod_{i=1}^{m}\left(x-t_{i}\right) \\
\omega_{i}(x) & =\omega_{\lrcorner}(x) /\left(x-t_{i}\right), \quad i=\overline{1, m} ; \\
l_{i}(x) & =\omega_{i}(x) / \omega_{i}\left(t_{i}\right), & i=\overline{1, m} ; \\
l_{m-1,\lrcorner}(f, x) & =\sum_{1}^{m} l_{i}(x) f\left(t_{i}\right)
\end{array}
$$

Further, denote

$$
z_{+}=\max (0, z), \quad z_{-}=\max (0,-z), \quad z_{ \pm}^{\prime}=z^{\prime} \cdot \operatorname{sign} z
$$

and introduce the functions

$$
\begin{align*}
S(x, \theta) & =\frac{1}{m!}(x-\theta)_{ \pm}^{m}-l_{m-1 . د}\left(\frac{1}{m!}(\cdot-\theta)_{ \pm}^{m}, x\right)  \tag{2.1}\\
& =\frac{1}{m!}(x-\theta)_{ \pm}^{m}-\frac{1}{m!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m}  \tag{2.2}\\
2 \cdot B(x, \theta) & =\frac{1}{(m-1)!}(x-\theta)_{ \pm}^{m-1}-l_{m-1 . د}\left(\frac{1}{(m-1)!}(\cdot-\theta)_{ \pm}^{m-1}, x\right)  \tag{2.3}\\
& =\frac{1}{(m-1)!}(x-\theta)_{ \pm}^{m-1}-\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-1} . \tag{2.4}
\end{align*}
$$

Note that based on the relations

$$
\begin{aligned}
& z_{ \pm}^{\prime}=(-1)^{l-1} z_{-}^{\prime}+z_{+}^{\prime}, \quad z^{\prime}=(-1)^{\prime} z_{-}^{\prime}+z_{+}^{\prime} \\
& z^{\prime}(\cdot)-l_{m-1 . \Delta}\left(z^{\prime}, \cdot\right) \equiv 0, \quad l=\overline{0, m-1}
\end{aligned}
$$

we can represent $B(x, \theta)$ in the form

$$
\begin{equation*}
B(x, \theta)=\frac{1}{(m-1)!}(x-\theta)_{+}^{m-1}-\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m-1} \tag{2.5}
\end{equation*}
$$

Finally, set

$$
\begin{aligned}
S_{l}(x, \theta)=\frac{\partial^{l}}{\partial x^{l}} S(x, \theta), & l=\overline{0, m} \\
B_{l}(x, \theta)=\frac{\partial^{l}}{\partial x^{l}} B(x, \theta), & l=\overline{0, m-1}
\end{aligned}
$$

Lemma A. Let

$$
\begin{gathered}
\omega_{m}^{(k)}(x)=c \prod_{j}\left(x-\alpha_{j}\right), \quad \alpha_{1}<\alpha_{2}<\cdots<\alpha_{m-1-k} \\
\omega_{1}^{(k)}(x)=c \prod_{j}\left(x-\beta_{j}\right), \quad \beta_{1}<\beta_{2}<\cdots<\beta_{m-1-k} \\
\alpha_{0}=a, \quad \beta_{0}=t_{1}, \quad \alpha_{m-k}=t_{m}, \quad \beta_{m-k}=b
\end{gathered}
$$

Then

$$
\alpha_{j} \leq \beta_{j} \leq \alpha_{j+1} \leq \beta_{j+1}
$$

and on each interval $\left(\beta_{j}, \alpha_{j+1}\right), j=\overline{0, m-1-k}$, the equalities

$$
\operatorname{sign} \omega_{i}^{(k)}(\cdot)=\operatorname{sign} \omega_{\Delta}^{(k+1)}(\cdot), \quad i=\overline{1, m}
$$

are calid.
The subsets $I_{m, k}(\Delta)$ and $J_{m, k}(\Delta)$ from Theorems A and 2 are defined as follows

$$
\begin{aligned}
& I_{m, k}(\Delta)=\bigcup_{j=0}^{m-k}\left[\alpha_{j}, \beta_{j}\right] \\
& J_{m, k}(\Delta)=\bigcup_{j=0}^{m-k-1}\left(\beta_{j}, \alpha_{j+1}\right) \subset\left(t_{1}, t_{m}\right)
\end{aligned}
$$

Moreover,

$$
\begin{align*}
I_{m, k}(\Delta) & =[a, b], \quad k=0 \\
J_{m, k}(\Delta) & =\left(t_{1}, t_{m}\right), \quad k=m-1 \\
\operatorname{mes} J_{m, k}(\Delta) & =\frac{k}{m-1}\left(t_{m}-t_{1}\right), \quad 0 \leq k \leq m-1 \tag{2.6}
\end{align*}
$$

Lemma B. For $f \in W_{x}^{\prime \prime \prime}[a, b]$

$$
f^{(k)}(x)-l_{m-1, \Delta}^{(k)}(f, x)=\int_{u}^{b} B_{k}(x, \theta) f^{(m)}(\theta) d \theta
$$

Lemma C. The kernel $B_{k}(x, \theta)=B_{k,\lrcorner}(x, \theta)$ has the following properties:
(i) if $x \in I_{m, k}(\Delta)$, then the function $B_{k}(x, \cdot)$ does not change its sign on the interval $[a, b]$;
(ii) if $x \in J_{m, k}(\Delta)$, then $\operatorname{supp} B_{k}(x, \cdot)=\left(t_{1}, t_{m}\right)$ and on the interval ( $t_{1}, t_{m}$ ) the function $B_{k}(x, \cdot)$ has exactly one zero $\theta=\theta_{x}$, this zero is a single one, and, therefore, $B_{k}(x, \cdot)$ changes its sign exactly once;
(iii) if $x \in\left(t_{1}, t_{m}\right)$, then

$$
\left.\frac{\partial^{\prime}}{\partial \theta^{\prime}} B_{k}(x, \theta)\right|_{\theta=t_{1}, t_{m}}=0, \quad l=\overline{0, m-2}
$$

Lemmas $A-C$ can be found in [6] (see also [2-3]). Lemma $A$ is derived from a theorem by V. A. Markov which states that if the roots of two polynomials are real and interlace, then the same is true for the roots of their derivatives [5, Corollary from Lemma 3]. Relation (2.6) is established in [3] following the idea from [1].

Theorem A follows from Lemma B and item (i) of Lemma C. From Lemma B and item (ii) of Lemma C one can conclude that for $x \in J_{m, k}(\Delta)$ the extremal function, which attains the supremum in (1.1), satisfies the relation

$$
f_{*}^{(m)}(x)= \pm \operatorname{sign}\left(x-\theta_{x}\right)
$$

Hence, with the aid of the equalities

$$
\frac{\partial^{m}}{\partial x^{m}} S(x, \theta)=\operatorname{sign}(x-\theta), \quad l_{m-1 . \Delta}(S(\cdot, \theta), x) \equiv 0
$$

we obtain
Lemma D. If $x \in J_{m, k}(\Delta)$, then

$$
L_{m, k}(\Delta, x)=\left|S_{k}\left(x, \theta_{x}\right)\right|
$$

with $\theta_{x}$ the unique point from $\left(t_{1}, t_{m}\right)$ such that

$$
B_{k}\left(x, \theta_{x}\right)=0
$$

## 3. Proof of Theorem 2

We will prove the following statement.
Theorem $2^{\prime}$. Let $1 \leq k \leq m-2, x \in\left(\beta_{j}, \alpha_{j+1}\right) \subset J_{m, k}(\Delta)$, and

$$
M_{k}(x)=S_{k}\left(x, \theta_{x}\right)
$$

where $\theta_{x}$ is such that

$$
\left|S_{k}\left(x, \theta_{x}\right)\right|=L_{m, k}(\Delta, x)
$$

If at any point $z \in\left(\beta_{j}, \alpha_{j+1}\right)$

$$
\begin{equation*}
M_{k}^{\prime}(z)=0 \tag{3.1}
\end{equation*}
$$

then

$$
\begin{equation*}
M_{k}(z) \cdot M_{k}^{\prime \prime}(z)>0 \tag{3.2}
\end{equation*}
$$

From (3.1)-(3.2) it follows that if the extremum of the function $L_{m, k}(\Delta, x)=\left|M_{k}(x)\right|$ on the interval ( $\beta_{j}, \alpha_{j+1}$ ) exists, then it must be the minimum, what proves that there is at most one such extrema, and this is exactly what Theorem 2 states.

Proof of Theorem 2'. Comparing (2.2) and (2.4), we see that

$$
\begin{equation*}
\frac{\partial}{\partial \theta} S_{l}(x, \theta)=-2 \cdot B_{l}(x, \theta), \quad l=\overline{0, m-1} \tag{3.3}
\end{equation*}
$$

Furthermore, set

$$
B_{l}^{\prime}(x, \theta)=\frac{\partial}{\partial \theta} B_{l}(x, \theta), \quad l=\overline{0, m-2}
$$

So, we have

$$
\begin{equation*}
M_{k}(x)=S_{k}\left(x, \theta_{x}\right) \tag{3.4}
\end{equation*}
$$

where by Lemma D

$$
\begin{equation*}
B_{k}\left(x, \theta_{x}\right)=0 \tag{3.5}
\end{equation*}
$$

Hence,

$$
\begin{aligned}
M_{k}^{\prime}(x) & =\left.\frac{\partial}{\partial x} S_{k}(x, \theta)\right|_{\theta=\theta_{1}}+\left.\frac{\partial}{\partial \theta} S_{k}(x, \theta)\right|_{\theta=\theta_{x}} \cdot \theta^{\prime}(x) \\
& =S_{k+1}\left(x, \theta_{x}\right)-2 \cdot B_{k}\left(x, \theta_{x}\right) \cdot \theta^{\prime}(x)
\end{aligned}
$$

Differentiating the identity $B_{k}(x, \theta(x)) \equiv 0$ with respect to $x$, we find

$$
\theta^{\prime}(x)=-B_{k+1}\left(x, \theta_{x}\right) / B_{k}^{\prime}\left(x, \theta_{x}\right),
$$

and since $\theta_{x}$ is a single zero of the function $B_{k}(x, \cdot)$, we have $B_{k}^{\prime}\left(x, \theta_{x}\right) \neq 0$, i.e., $\left|\theta^{\prime}(x)\right|<\infty$.

Thus,

$$
M_{k}^{\prime}(x)=S_{k+1}\left(x, \theta_{x}\right),
$$

and, therefore,

$$
\begin{equation*}
S_{k+1}\left(z, \theta_{z}\right)=0 \tag{3.6}
\end{equation*}
$$

Further,

$$
\begin{aligned}
M_{k}^{\prime \prime}(x) & =\left.\frac{\partial}{\partial x} S_{k+1}(x, \theta)\right|_{\theta=\theta_{x}}+\left.\frac{\partial}{\partial \theta} S_{k+1}(x, \theta)\right|_{\theta=\theta_{x}} \cdot \theta^{\prime}(x) \\
& =S_{k+2}\left(x, \theta_{x}\right)-2 \cdot B_{k+1}\left(x, \theta_{x}\right) \cdot \theta^{\prime}(x) \\
& =S_{k+2}\left(x, \theta_{x}\right)+2 \cdot B_{k+1}^{2}\left(x, \theta_{x}\right) / B_{k}^{\prime}\left(x, \theta_{x}\right) .
\end{aligned}
$$

Using (3.4) we finally obtain
$M_{k}(x) \cdot M_{k}^{\prime \prime}(x)=\frac{S_{k}\left(x, \theta_{x}\right)}{B_{k}^{\prime}\left(x, \theta_{x}\right)}\left(S_{k+2}\left(x, \theta_{x}\right) \cdot B_{k}^{\prime}\left(x, \theta_{x}\right)+2 \cdot B_{k+1}^{2}\left(x, \theta_{x}\right)\right)$.

Let us show that the inequalities

$$
\begin{align*}
\frac{S_{k}\left(z, \theta_{z}\right)}{B_{k}^{\prime}\left(z, \theta_{z}\right)} & >0  \tag{3.7}\\
\left|B_{k}^{\prime}\left(z, \theta_{z}\right)\right| & <\left|B_{k+1}\left(z, \theta_{z}\right)\right|,  \tag{3.8}\\
\left|S_{k+2}\left(z, \theta_{z}\right)\right| & <\left|2 \cdot B_{k+1}\left(z, \theta_{z}\right)\right|, \tag{3.9}
\end{align*}
$$

are valid, which proves (3.2).

Define the functions $p(x, \theta)$ and $q(x, \theta)$ by the identities

$$
\begin{align*}
& B^{\prime}(x, \theta)=-B_{1}(x, \theta)+\frac{1}{2} p(x, \theta)  \tag{3.10}\\
& S_{1}(x, \theta)=2 \cdot B(x, \theta)+q(x, \theta) \tag{3.11}
\end{align*}
$$

and note that for each $\theta \in \mathbb{R}$ the functions $p_{\theta}(\cdot) \equiv p(\cdot, \theta), q_{\theta}(\cdot) \equiv q(\cdot, \theta)$ are algebraic polynomials of degree $m-1$. Then

$$
\begin{align*}
B_{k}^{\prime}\left(x, \theta_{x}\right) & =-B_{k+1}\left(x, \theta_{x}\right)+\frac{1}{2} p_{\theta_{x}}^{(k)}(x),  \tag{3.12}\\
S_{k+2}\left(x, \theta_{x}\right) & =2 \cdot B_{k+1}\left(x, \theta_{x}\right)+q_{\theta_{x}}^{(k+1)}(x) \tag{3.13}
\end{align*}
$$

Moreover, by (3.5)-(3.6)

$$
\begin{equation*}
q_{\theta_{z}}^{(k)}(z)=S_{k+1}\left(z, \theta_{z}\right)-2 \cdot B_{k}\left(z, \theta_{z}\right)=0 . \tag{3.14}
\end{equation*}
$$

The proofs of inequalities (3.7)-(3.9) are based on relations (3.12)-(3.14) and on the following three lemmas, which will be established below.

Lemma 1. If $x \in J_{m, k}(\Delta)$ and $B_{k}\left(x, \theta_{x}\right)=0$, then

$$
\begin{align*}
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =\operatorname{sign} B_{k}^{\prime}\left(x, \theta_{x}\right)  \tag{3.15}\\
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =-\operatorname{sign} \omega_{\Delta}^{(k+1)}(x),  \tag{3.16}\\
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =\operatorname{sign} B_{k-1}\left(x, \theta_{x}\right),  \tag{3.17}\\
\operatorname{sign} B_{k-1}\left(x, \theta_{x}\right) & =-\operatorname{sign} B_{k+1}\left(x, \theta_{x}\right), \tag{3.18}
\end{align*}
$$

and for $x=z$, i.e., if $S_{k+1}\left(x, \theta_{x}\right)=0$, moreover,

$$
\begin{equation*}
\operatorname{sign} S_{k}\left(x, \theta_{x}\right)=-\operatorname{sign} S_{k+2}\left(x, \theta_{x}\right) \tag{3.19}
\end{equation*}
$$

Lemma 2. If $x \in J_{m, k}(\Delta)$, then for any $\theta \in\left(t_{1}, t_{m}\right)$

$$
\operatorname{sign} p_{\theta}^{(k)}(x)=\operatorname{sign} \omega_{\Delta}^{(k+1)}(x)
$$

Lemma 3. If $\theta \in\left(t_{1}, t_{m}\right)$ and $q_{\theta}^{(k)}(x)=0$, then

$$
\operatorname{sign} q_{\theta}^{(k+1)}(x)=-\operatorname{sign} \omega_{\Delta}^{(k+1)}(x)
$$

From Lemma 1 there follow the equalities

$$
\begin{align*}
\operatorname{sign} B_{k}^{\prime}\left(z, \theta_{z}\right) & =-\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right),  \tag{3.20}\\
\operatorname{sign} S_{k+2}\left(z, \theta_{z}\right) & =\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right)  \tag{3.21}\\
\operatorname{sign} \omega_{\Delta}^{(k+1)}(z) & =\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right) \tag{3.22}
\end{align*}
$$

From Lemma 2 with the aid of (3.22) we derive

$$
\begin{equation*}
\operatorname{sign} p_{\theta_{z}}^{(k)}(z)=\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right) \tag{3.23}
\end{equation*}
$$

From Lemma 3, using (3.14) and with the aid of (3.22) we obtain

$$
\begin{equation*}
\operatorname{sign} q_{\theta_{z}}^{(k+1)}(z)=-\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right) . \tag{3.24}
\end{equation*}
$$

Putting together (3.20) and (3.23), we have

$$
\operatorname{sign} B_{k}^{\prime}\left(z, \theta_{z}\right)=\operatorname{sign}\left\{-B_{k+1}\left(z, \theta_{z}\right)\right\}=-\operatorname{sign} p_{\theta_{z}}^{(k)}(z),
$$

which by comparison with (3.12) proves (3.8).
Similarly, combining (3.21) and (3.24) we obtain

$$
\operatorname{sign} S_{k+2}\left(z, \theta_{z}\right)=\operatorname{sign} B_{k+1}\left(z, \theta_{z}\right)=-\operatorname{sign} q_{\theta_{z}}^{(k+1)}(z),
$$

and with the aid of (3.13) it proves (3.9).
Finally, inequality (3.7) is equal to (3.15). Theorem $2^{\prime}$ and, thus, Theorem 2 are proved.

As we pointed out in the introduction, there is a complete similarity between Theorems A and 2, which describe the behaviour of $L_{m, k}(\Delta, x)$, and V. A. Markov's results [5] on the function $N_{m, k}(x)$ (see Eq. (1.4)). The situation becomes different if we consider the behaviour of derivatives. V. A. Gusev [1] has shown that the function $N_{m, k}^{\prime}(x)$ is continuous, while $N_{m, k}^{\prime \prime}(x)$ has discontinuities of the 1 st kind. We give without proof the following statement on the function $L_{m, k}^{\prime}(\Delta, x)$.

Proposition. The function $L_{m, k}^{\prime}(\Delta, x)$ is continuous everywhere except at the points $\left\{\alpha_{j}, \beta_{j}\right\}_{j=1}^{m-k-1}$, where it has discontinuities of the 1 st kind. Moreover,

$$
\begin{aligned}
\left|L_{m, k}^{\prime}\left(\Delta, \alpha_{j}-0\right)\right| & =\left|S_{k+1}\left(\alpha_{j}, t_{m-1}\right)\right| \\
& \neq\left|S_{k+1}\left(\alpha_{j}, t_{m}\right)\right|=\frac{1}{m!}\left|\omega_{د}^{(k+1)}\left(\alpha_{j}\right)\right|=\left|L_{m, k}^{\prime}\left(\Delta ; \alpha_{j}+0\right)\right| \\
\left|L_{m, k}^{\prime}\left(\Delta, \beta_{j}-0\right)\right| & =\frac{1}{m!}\left|\omega_{\Delta}^{(k+1)}\left(\beta_{j}\right)\right|=\left|S_{k+1}\left(\beta_{j}, t_{1}\right)\right| \\
& \neq\left|S_{k+1}\left(\beta_{j}, t_{2}\right)\right|=\left|L_{m, k}^{\prime}\left(\Delta, \beta_{j}+0\right)\right|
\end{aligned}
$$

The points $\left\{\alpha_{j}, \beta_{j}\right\}_{j=1}^{m-k-1}$ appear to be the breakpoints of $L_{m, k}^{\prime}(\Delta, x)$ due to the fact [6] that

$$
\begin{array}{ll}
\operatorname{supp} B_{k}(x, \cdot)=\left(t_{1}, t_{m-1}\right), & x \in\left\{\alpha_{j}\right\}_{j=1}^{m-k-1} \\
\operatorname{supp} B_{k}(x, \cdot)=\left(t_{2}, t_{m}\right), & x \in\left\{\beta_{j}\right\}_{j=1}^{m-k-1}
\end{array}
$$

while

$$
\operatorname{supp} B_{k}(x, \cdot)=\left(t_{1}, t_{m}\right), \quad x \in\left(t_{1}, t_{m}\right) \backslash\left\{\alpha_{j}, \beta_{j}\right\}_{j=1}^{m-k-1}
$$

Let us emphasize that at the points $\beta_{0}=t_{1}$ and $\alpha_{m-k}=t_{m}$ the function $L_{m, k}^{\prime}(\Delta, x)$ is continuous.
4. Auxiliary Properties of the Functions $B(x, \theta)$ and $S(x, \theta)$

Lemma 4. For arbitrary mesh $\Delta_{m}$, and for any $x, \theta \in \mathbb{R}$

$$
\begin{equation*}
S(x, \theta)=2 \cdot \frac{1}{m}(x-\theta) B(x, \theta)+c(\theta) \frac{1}{m!} \omega(x) \tag{4.1}
\end{equation*}
$$

where

$$
c(\theta)=\sum_{i=1}^{m} \frac{\left(t_{i}-\theta\right)_{ \pm}^{m-1}}{\omega_{i}\left(t_{i}\right)}= \begin{cases}1, & \theta \leq t_{1}  \tag{4.2}\\ c_{\theta} \in(-1,1), & t_{1}<\theta<t_{m} \\ -1, & t_{m} \leq \theta\end{cases}
$$

Proof. By (2.2), (2.4)

$$
S\left(t_{i}, \theta\right)=0, \quad B\left(t_{i}, \theta\right)=0, \quad i=\overline{1, m}
$$

and since the difference

$$
\begin{aligned}
& S(x, \theta)-2 \cdot \frac{1}{m}(x-\theta) B(x, \theta) \\
& \quad=\frac{1}{m!}(x-\theta) \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-1}-\frac{1}{m!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m}
\end{aligned}
$$

is a polynomial of degree $m$ with respect to $x$, we obtain

$$
S(x, \theta)=2 \cdot \frac{1}{m}(x-\theta) B(x, \theta)+c(\theta) \frac{1}{m!} \omega(x)
$$

with

$$
c(\theta)=\sum_{i=1}^{m} \frac{\left(t_{i}-\theta\right)_{ \pm}^{m-1}}{\omega_{i}\left(t_{i}\right)} .
$$

To prove the right-hand side of (4.2) let us introduce the classical B-spline $b(t)$ of degree $m-2$, defined on the mesh $\Delta_{m}$ by the formulas

$$
\begin{aligned}
b(t) & =(m-1) \sum_{i=1}^{m} \frac{\left(t_{i}-t\right)_{+}^{m-2}}{\omega_{\Delta}^{\prime}\left(t_{i}\right)} \\
& =(-1)^{m-1}(m-1) \sum_{i=1}^{m} \frac{\left(t-t_{i}\right)_{+}^{m-2}}{\omega_{\lrcorner}^{\prime}\left(t_{i}\right)}
\end{aligned}
$$

with the properties

$$
\operatorname{supp} b(\cdot)=\left(t_{1}, t_{m}\right), \quad b(\cdot) \geq 0, \quad \int_{t_{1}}^{t_{m}} b(t) d t=1
$$

From the equalities

$$
\begin{gathered}
(m-1) \int_{\theta}^{t_{m}}\left(t_{i}-t\right)_{+}^{m-2} d t=\left(t_{i}-\theta\right)_{+}^{m-1} \\
(m-1) \int_{t_{1}}^{\theta}\left(t-t_{i}\right)_{+}^{m-2} d t=\left(\theta-t_{i}\right)_{+}^{m-1}=\left(t_{i}-\theta\right)_{-}^{m-1} \\
\left(t_{i}-\theta\right)_{ \pm}^{m-1}=(-1)^{m-2}\left(t_{i}-\theta\right)_{-}^{m-1}+\left(t_{i}-\theta\right)_{+}^{m-1}
\end{gathered}
$$

we conclude that

$$
c(\theta)=\int_{\theta}^{t_{m}} b(t) d t-\int_{t_{1}}^{\theta} b(t) d t,
$$

and the right-hand side equality in (4.2) follows now from the properties of B-splines.

Lemma 5. Let $\theta \in\left(t_{1}, t_{m}\right), k=\overline{1, m-2}$. If

$$
B_{k}(y, \theta)=0, \quad y \in\left(t_{1}, t_{m}\right)
$$

then

$$
\begin{equation*}
B_{k-1}(y, \theta) \cdot B_{k+1}(y, \theta)<0 \tag{4.3}
\end{equation*}
$$

Lemma 6. Let $\theta \in\left(t_{1}, t_{m}\right), k=\overline{1, m-2}$. If

$$
S_{k+1}(y, \theta)=0, \quad y \in\left(t_{1}, t_{m}\right)
$$

then

$$
\begin{equation*}
S_{k}(y, \theta) \cdot S_{k+2}(y, \theta) \leq 0 . \tag{4.4}
\end{equation*}
$$

Proofs of Lemmas 5 and 6. Each of the functions $B(\cdot, \theta)$ and $S(\cdot, \theta)$ has $m$ zeroes at the points $x=t_{i}, i=\overline{1, m}$. Moreover, their higher derivatives

$$
\begin{aligned}
B_{m-1}(\cdot, \theta) & =\frac{1}{2} \operatorname{sign}(\cdot-\theta)-\frac{1}{2} c(\theta) \\
S_{m}(\cdot, \theta) & =\operatorname{sign}(\cdot-\theta)
\end{aligned}
$$

have exactly one change of sign on ( $t_{1}, t_{m}$ ). Therefore, by Rolle's Theorem, for the number $\nu$ of zeroes of the functions $B_{l}(\cdot, \theta)$ and $S_{l}(\cdot, \theta)$ on the interval $\left[t_{1}, t_{m}\right]$ we have

$$
\begin{align*}
\nu\left[B_{l}(\cdot, \theta)\right] & =m-l, & & l=\overline{0, m-2} ;  \tag{4.5}\\
m-l & \leq \nu\left[S_{l}(\cdot, \theta)\right] \leq m+1-l, & & l=\overline{0, m-1}, \tag{4.6}
\end{align*}
$$

If, for instance, (4.4) does not hold, then the interval linking the separated zeroes of the function $S_{k}(\cdot, \theta)$, closest to the point $y$, contains 3 zeroes of $S_{k+1}(\cdot, \theta)$, and if we add to this number $m-(k+2)$ zeroes of $S_{k+1}(\cdot, \theta)$, which are contained between the other zeroes of $S_{k}(\cdot, \theta)$, we will come to a contradiction with (4.6). The proof of (4.3) is obtained in the same manner.

Remark. As it was pointed out by one of the referees the precise statement of (4.4) is a strong inequality, and also the sharp statement of (4.6) is

$$
\nu\left[S_{l}(\cdot, \theta)\right]=m+1-l, \quad l=\overline{0, m-1} .
$$

But such a refinement will not be required in the following considerations.
Lemma 7. Let $\theta \in\left(t_{1}, t_{m}\right)$. Then

$$
\operatorname{sign} B(\cdot, \theta)=\operatorname{sign} \omega(\cdot)
$$

Proof. By (4.5) the function $B(\cdot, \theta)$ has its zeroes only at the points $\left\{t_{i}\right\}_{1}^{m}$, and each of them are simple. Hence

$$
\operatorname{sign} B(\cdot, \theta)= \pm \operatorname{sign} \omega(\cdot) .
$$

It remains to investigate the sign of $B(x, \theta)$ for $x \rightarrow+\infty$. We have

$$
\begin{aligned}
2 \cdot B(x, \theta) & =\frac{1}{(m-1)!}(x-\theta)_{ \pm}^{m-1}-\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-1} \\
& =\frac{1}{(m-1)!}(x-\theta)^{m-1}-\frac{1}{(m-1)!} r_{m-1, \theta}(x), \quad x \rightarrow+\infty
\end{aligned}
$$

where by (4.2) the leading coefficient of the polynomial $r_{m-1, \theta}(x)$ is equal to

$$
\sum_{i=1}^{m} \frac{\left(t_{i}-\theta\right)_{ \pm}^{m-1}}{\omega_{i}\left(t_{i}\right)}=c(\theta)<1
$$

Hence,

$$
\operatorname{sign} B(x, \theta)=\operatorname{sign} \omega(x)>0, \quad x \rightarrow+\infty
$$

and the lemma is proved.
Corollary. Let $\theta \in\left(t_{1}, t_{m}\right)$. Then

$$
\operatorname{sign} B_{1}\left(t_{i}, \theta\right)=\operatorname{sign} \omega_{i}\left(t_{i}\right), \quad i=\overline{1, m}
$$

Proof. Since

$$
B\left(t_{i}, \theta\right)=\omega\left(t_{i}\right)=0
$$

and by Lemma 7

$$
\operatorname{sign} B(\cdot, \theta)=\operatorname{sign} \omega(\cdot)
$$

we have only to make use of the definitions

$$
B_{1}\left(t_{i}, \theta\right)=\left.\frac{\partial}{\partial x} B(x, \theta)\right|_{x=t_{i}}, \quad \omega_{i}\left(t_{i}\right)=\left.\frac{\partial}{\partial x} \omega(x)\right|_{x-t_{i}}
$$

## 5. Proof of Lemma 1

Let us recall the statements we are going to prove, preserving their enumeration from Section 3.

Lemma 1. If $x \in J_{m, k}(\Delta)$ and $B_{k}\left(x, \theta_{x}\right)=0$, then

$$
\begin{align*}
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =\operatorname{sign} B_{k}^{\prime}\left(x, \theta_{x}\right),  \tag{3.15}\\
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =-\operatorname{sign} \omega_{3}^{(k+1)}(x),  \tag{3.16}\\
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =\operatorname{sign} B_{k-1}\left(x, \theta_{x}\right),  \tag{3.17}\\
\operatorname{sign} B_{k-1}\left(x, \theta_{x}\right) & =-\operatorname{sign} B_{k+1}\left(x, \theta_{x}\right), \tag{3.18}
\end{align*}
$$

and for $x=z$, i.e., if $S_{k+1}\left(x, \theta_{x}\right)=0$, moreover,

$$
\begin{equation*}
\operatorname{sign} S_{k}\left(x, \theta_{x}\right)=-\operatorname{sign} S_{k+2}\left(x, \theta_{x}\right) \tag{3.19}
\end{equation*}
$$

5.1. Proof of Equality (3.15). Since

$$
S^{(m)}(x, \theta)=\frac{\partial^{m}}{\partial x^{m}} S(x, \theta)=\operatorname{sign}(x-\theta),
$$

by Lemma B we have

$$
S_{k}\left(x, \theta_{x}\right)=S^{(k)}\left(x, \theta_{x}\right)=-\int_{a}^{\theta_{x}} B_{k}(x, \theta) d \theta+\int_{\theta_{x}}^{b} B_{k}(x, \theta) d \theta
$$

By Lemma $C$, item (ii) the function $B_{k}(x, \cdot)$ on the interval ( $\left.t_{1}, t_{m}\right)$ has the unique simple zero at the point $\theta_{x}$, therefore,

$$
\begin{align*}
\operatorname{sign} S_{k}\left(x, \theta_{x}\right) & =\operatorname{sign} B_{k}\left(x, \theta_{x}+0\right)  \tag{5.1}\\
& =\operatorname{sign} B_{k}\left(x, t_{m}-0\right) \tag{5.2}
\end{align*}
$$

By the same arguments

$$
\operatorname{sign} B_{k}^{\prime}\left(x, \theta_{x}\right)=\operatorname{sign} B_{k}\left(x, \theta_{x}+0\right)
$$

thus, by (5.1)

$$
\operatorname{sign} S_{k}\left(x, \theta_{x}\right)=\operatorname{sign} B_{k}^{\prime}\left(x, \theta_{x}\right)
$$

5.2. Proof of Equality (3.16). Differentiating (2.5) $k$ times with respect to $x$, we obtain

$$
\begin{aligned}
B_{k}(x, \theta)= & \frac{1}{(m-1-k)!}(x-\theta)_{+}^{m-1-k} \\
& -\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}^{(k)}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m-1}
\end{aligned}
$$

Hence we conclude that

$$
B_{k}(x, \theta)=-\frac{c_{m} \omega_{m}^{(k)}(x)}{\omega_{m}\left(t_{m}\right)}\left(t_{m}-\theta\right)^{m-1}, \quad \max \left(x, t_{m-1}\right)<\theta<t_{m}
$$

and, therefore,

$$
\operatorname{sign} B_{k}\left(x, t_{m}-0\right)=-\operatorname{sign} \omega_{m}^{(k)}(x) \cdot \operatorname{sign} \omega_{m}\left(t_{m}\right) .
$$

## Obviously,

$$
\operatorname{sign} \omega_{t n}\left(t_{m}\right)>0 ;
$$

by Lemma A

$$
\operatorname{sign} \omega_{m}^{(k)}(x)=\operatorname{sign} \omega_{\Delta}^{(k+1)}(x)
$$

by (5.2)

$$
\operatorname{sign} B_{k}\left(x, t_{m}-0\right)=\operatorname{sign} S_{k}\left(x, \theta_{x}\right) ;
$$

i.e.,

$$
\operatorname{sign} S_{k}\left(x, \theta_{x}\right)=-\operatorname{sign} \omega_{\lrcorner}^{(k+1)}(x),
$$

which was to be proved
5.3. Proof of Equality (3.17). Differentiating both sides of (4.1) $k$ times with respect to $x$ and substituting $\theta=\theta_{x}$, with regards for the equality $B_{k}\left(x, \theta_{x}\right)=0$, we obtain

$$
S_{k}\left(x, \theta_{x}\right)=2 \cdot \frac{k}{m} B_{k-1}\left(x, \theta_{x}\right)+c\left(\theta_{x}\right) \frac{1}{m!} \omega^{(k)}(x) .
$$

However, by virtue of (4.2)

$$
\left|c\left(\theta_{x}\right)\right|<1
$$

and by Lemma D

$$
\left|S_{k}\left(x, \theta_{x}\right)\right|>\frac{1}{m!}\left|\omega^{(k)}(x)\right| .
$$

Thus

$$
\operatorname{sign} S_{k}\left(x, \theta_{x}\right)=\operatorname{sign} B_{k-1}\left(x, \theta_{x}\right),
$$

and (3.17) is established.
5.4. Proof of Equalities (3.18)-(3.19). These follow from Lemmas 4-5.

Lemma 1 is completely proved.

## 6. Proof of Lemma 2

Lemma 2. Let $p_{\theta}(x)=p(x, \theta)$ be the function defined by equality

$$
\begin{equation*}
B^{\prime}(x, \theta)=-B_{1}(x, \theta)+\frac{1}{2} p(x, \theta) \tag{3.10}
\end{equation*}
$$

If $x \in J_{m, k}(\Delta)$, then for any $\theta \in\left(t_{1}, t_{m}\right)$

$$
\operatorname{sign} p_{\theta}^{(k)}(x)=\operatorname{sign} \omega_{د}^{(k+1)}(x)
$$

Proof of Lemma 2. From definitions (3.10) and (2.4) it follows that for any $\theta \in\left(t_{1}, t_{m}\right)$

$$
\begin{aligned}
p_{\theta}(x)= & 2 \cdot B^{\prime}(x, \theta)+2 \cdot B_{1}(x, \theta) \\
= & \frac{1}{(m-2)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-2} \\
& -\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-1}
\end{aligned}
$$

i.e., $p_{\theta}(x)$ is a polynomial of degree $m-1$ with respect to $x$. Moreover,

$$
p_{\theta}\left(t_{i}\right)=2 \cdot B^{\prime}\left(t_{i}, \theta\right)+2 \cdot B_{1}\left(t_{i}, \theta\right), \quad i=\overline{1, m}
$$

However, by virtue of (2.3)-(2.4)

$$
\begin{aligned}
-2 \cdot & B^{\prime}(x, \theta) \\
& =-\frac{\partial}{\partial \theta} 2 \cdot B(x, \theta) \\
& =\frac{1}{(m-2)!}(x-\theta)_{ \pm}^{m-2}-I_{m-1, \Delta}\left(\frac{1}{(m-2)!}(\cdot-\theta)_{ \pm}^{m-2}, x\right)
\end{aligned}
$$

whence

$$
B^{\prime}\left(t_{i}, \theta\right)=0, \quad i=\overline{1, m}
$$

and, therefore,

$$
p_{\theta}\left(t_{i}\right)=2 \cdot B_{1}\left(t_{i}, \theta\right), \quad i=\overline{1, m}
$$

By the Lagrange interpolation formula

$$
p_{\theta}(x)=\sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)} p_{\theta}\left(t_{i}\right)=2 \cdot \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)} B_{l}\left(t_{i}, \theta\right),
$$

hence,

$$
p_{\theta}^{(k)}(x)=2 \cdot \sum_{i=1}^{m} \frac{B_{1}\left(t_{i}, \theta\right)}{\omega_{i}\left(t_{i}\right)} \omega_{i}^{(k)}(x) .
$$

By the corollary of Lemma 7 for $\boldsymbol{\theta} \in\left(t_{1}, t_{m}\right)$

$$
\operatorname{sign} B_{1}\left(t_{i}, \theta\right)=\operatorname{sign} \omega_{i}\left(t_{i}\right), \quad i=\overline{1, m} .
$$

By Lemma A for $x \in J_{m, k}(\Delta)$

$$
\operatorname{sign} \omega_{i}^{(k)}(x)=\operatorname{sign} \omega_{\lambda}^{(k+1)}(x), \quad i=\overline{1, m} .
$$

Thus, for $x \in J_{m, k}(\Delta)$ and $\theta \in\left(t_{1}, t_{m}\right)$

$$
\operatorname{sign} p_{\theta}^{(k)}(x)=\operatorname{sign} \omega_{\lrcorner}^{(k+1)}(x),
$$

and Lemma 2 is proved.

## 7. Proof of Lemma 3

Lemma 3. Let $q_{\theta}(x)=q(x, \theta)$ be the function defined by equality

$$
\begin{equation*}
S_{1}(x, \theta)=2 \cdot B(x, \theta)+q(x, \theta) . \tag{3.11}
\end{equation*}
$$

If $\theta \in\left(t_{1}, t_{m}\right)$ and $q_{\theta}^{(k)}(x)=0$, then

$$
\operatorname{sign} q_{\theta}^{(k+1)}(x)=-\operatorname{sign} \omega_{A}^{(k+1)}(x)
$$

Proof of Lemma 3. From Eqs. (3.11), (2.2), and (2.4) it follows that for any $\theta \in \mathbb{R}$

$$
\begin{aligned}
q_{\theta}(x) & =S_{1}(x, \theta)-2 \cdot B(x, \theta) \\
& =\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m-1}-\frac{1}{m!} \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{ \pm}^{m},
\end{aligned}
$$

i.e., $q_{\theta}(x)$ is a polynomial of degree $m-1$ with respect to $x$ with leading
coefficient equal to

$$
\frac{1}{(m-1)!} c(\theta)=\frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\left(t_{i}-\theta\right)_{+}^{m-1}}{\omega_{i}\left(t_{i}\right)} .
$$

We need two lemmas. The first of them is due to V. A. Markov, and the other will be proved in the next section.

Lemma 8 [5, Lemma 2]. Let

$$
\begin{aligned}
& r(x)=\prod_{j=1}^{s}\left(x-\mu_{j}\right), \quad \mu_{1}<\mu_{2}<\cdots<\mu_{s}, \\
& r_{j}(x)=r(x) /\left(x-\mu_{j}\right) .
\end{aligned}
$$

If

$$
r^{(i)}(\xi)=0,
$$

then

$$
\operatorname{sign} r_{j}^{(l)}(\xi)=\operatorname{sign} r^{(l+1)}(\xi), \quad j=\overline{1, s} .
$$

Lemma 9. For any $\theta \in\left(t_{1}, t_{m}\right)$ zeroes of the polynomials $q_{\theta}(x)$ and $\omega_{\Delta}^{\prime}(x)$ interlace. Moreoter, if

$$
\begin{aligned}
q_{\theta}(x) & =\frac{1}{(m-1)!} c(\theta) \prod_{j}\left(x-\delta_{j}(\theta)\right) \\
\delta_{1}(\theta) & <\delta_{2}(\theta)<\cdots<\delta_{m-1}(\theta) \\
\omega_{د}^{\prime}(x) & =m \prod_{j}\left(x-\tau_{j}\right), \quad \tau_{1}<\tau_{2}<\cdots<\tau_{m-1}
\end{aligned}
$$

then

$$
\begin{array}{rr}
\delta_{1}(\theta)<\tau_{1}<\delta_{2}(\theta)<\tau_{2}<\cdots<\delta_{m-1}(\theta)<\tau_{m-1}, & c(\theta) \geq 0 \\
\tau_{1}<\delta_{1}(\theta)<\tau_{2}<\delta_{2}(\theta)<\cdots<\tau_{m-1}<\delta_{m-1}(\theta), & c(\theta) \leq 0 . \tag{7.2}
\end{array}
$$

Corollary. For any $\theta \in\left(t_{1}, t_{m}\right)$

$$
\operatorname{sign} \omega_{د}^{\prime}\left(\delta_{j}\right)=-\operatorname{sign} q_{\theta}^{\prime}\left(\delta_{j}\right)
$$

Having these statements, we can now prove Lemma 3 repeating arguments from V. A. Markov [5, Lemma 3].

By the Lagrange interpolation formula

$$
\omega_{\Delta}^{\prime}(x)=\sum_{j=1}^{m} \frac{\omega_{\Delta}^{\prime}\left(\delta_{j}\right)}{q_{\theta}^{\prime}\left(\delta_{j}\right)} q_{\theta, j}(x)+c q_{\theta}(x),
$$

where

$$
q_{\theta, j}(x)=q_{\theta}(x) /\left(x-\delta_{j}\right)
$$

and if

$$
q_{\theta}^{(k)}(x)=0,
$$

then

$$
\omega_{\Delta}^{(k+1)}(x)=\sum_{j=1}^{m} \frac{\omega_{j}^{\prime}\left(\delta_{j}\right)}{q_{\theta}^{\prime}\left(\delta_{j}\right)} q_{\theta, j}^{(k)}(x) .
$$

By Lemma 8

$$
\operatorname{sign} q_{\theta, j}^{(k)}(x)=\operatorname{sign} q_{\theta}^{(k+1)}(x) .
$$

By corollary of Lemma 9

$$
\operatorname{sign} \omega_{\Delta}^{\prime}\left(\delta_{j}\right)=-\operatorname{sign} q_{\theta}^{\prime}\left(\delta_{j}\right)
$$

Hence

$$
\operatorname{sign} \omega_{\Delta}^{(k+1)}(x)=-\operatorname{sign} q_{\theta}^{(k+1)}(x),
$$

which was stated in Lemma 3.

## 8. Proof of Lemma 9

We will prove the following equivalent statement.
Lemma 9'. Let $q_{\theta}(x)=q(x, \theta)$ be the function defined by equality

$$
\begin{equation*}
S_{1}(x, \theta)=2 \cdot B(x, \theta)+q(x, \theta) \tag{3.11}
\end{equation*}
$$

and let

$$
\omega_{\Delta}^{\prime}(x)=m \prod_{j}\left(x-\tau_{j}\right), \quad \tau_{1}<\tau_{2}<\cdots<\tau_{m-1} .
$$

Then

$$
\begin{equation*}
\operatorname{sign} q_{\theta}\left(\tau_{j}\right)=\operatorname{sign} q\left(\tau_{j}, \theta\right)=(-1)^{m-1-j}, \quad \theta \in\left(t_{1}, t_{m}\right) \tag{8.1}
\end{equation*}
$$

Equalities (8.1) mean that zeroes of the polynomials $q_{\theta}(x)$ and $\omega^{\prime}(x)$ interlace. To obtain relations (7.1)-(7.2) we must only take into account the sign of the leading coefficient of the polynomial $q_{\theta} \in P_{m-1}$.

Proof of Lemma 9'. Let

$$
\omega_{د}^{\prime}(\xi)=0, \quad \xi \in\left\{\tau_{1}, \tau_{2}, \ldots, \tau_{m-1}\right\}
$$

Let us calculate zeroes of the function $q_{x}(\cdot) \equiv q(x, \cdot)$ on the interval $\left[t_{1}, t_{m}\right]$ for $x=\xi$.

By (3.3) and item (iii) of Lemma 3

$$
\begin{aligned}
\left.\frac{\partial^{l}}{\partial \theta^{l}} q(x, \theta)\right|_{\theta-t_{1}, t_{m}} & =\left.\frac{\partial^{l}}{\partial \theta^{l}} S_{1}(x, \theta)\right|_{\theta=t_{1}, t_{m}}-\left.2 \cdot \frac{\partial^{l}}{\partial \theta^{l}} B(x, \theta)\right|_{\theta-t_{1}, t_{m}, \ldots} \\
& = \begin{cases}\left.S_{1}(x, \theta)\right|_{\theta-t_{1}, t_{m}}, & l=0, \\
0, & 1 \leq l \leq m-2 .\end{cases}
\end{aligned}
$$

Differentiating both sides of (4.1) with respect to $x$, we find

$$
S_{1}(x, \theta)=2 \cdot \frac{1}{m}(x-\theta) B_{1}(x, \theta)+2 \cdot \frac{1}{m} B(x, \theta)+c(\theta) \frac{1}{m!} \omega^{\prime}(x)
$$

whence, using again the finiteness of $B_{l}(x, \cdot)$, with the aid of (4.2) we obtain

$$
\begin{aligned}
\left.S_{1}(x, \theta)\right|_{\theta=t_{1}, t_{1, \prime}} & =\left.c(\theta) \frac{1}{m!} \omega^{\prime}(x)\right|_{\theta=t_{1}, t_{m}} \\
& =\left\{\begin{array}{cl}
\frac{1}{m!} \omega^{\prime}(x), & \theta=t_{1}, \\
-\frac{1}{m!} \omega^{\prime}(x), & \theta=t_{m} .
\end{array}\right.
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\left.q_{\xi}^{(l)}(\theta)\right|_{\theta=r_{1}, l_{m}}=\left.\frac{\partial^{l}}{\partial \theta^{l}} q(\xi, \theta)\right|_{\theta=t_{1}, t_{, n}}=0, \quad l=\overline{0, m-2} . \tag{8.2}
\end{equation*}
$$

On the other hand, by (3.11) and (3.3)

$$
q_{x}^{\prime}(\theta)=-2 \cdot B_{1}(x, \theta)-2 \cdot B^{\prime}(x, \theta)
$$

and using for $B(x, \theta)$ representation (2.5) we obtain

$$
\begin{aligned}
\frac{1}{2} q_{i}^{\prime}(\theta)= & \frac{1}{(m-1)!} \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m-1} \\
& -\frac{1}{(m-2)!} \sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m-2}
\end{aligned}
$$

From this relation by differentiating $m-2$ times with respect to $\theta$, taking into account the equalities

$$
\frac{\partial}{\partial \theta}\left(t_{i}-\theta\right)_{+}^{\prime}=(-l) \cdot\left(t_{i}-\theta\right)_{+}^{l-1}, \quad\left(t_{i}-\theta\right)_{+}^{\prime}=\left(t_{i}-\theta\right)_{+}^{l-1} \cdot\left(t_{i}-\theta\right)
$$

we derive

$$
\begin{aligned}
(-1)^{m-2} & \frac{1}{2} q_{x}^{(m-1)}(\theta) \\
& =\sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x) \cdot\left(t_{i}-\theta\right)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0}-\sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0} \\
= & \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x) \cdot\left(t_{i}-x\right)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0}-\sum_{i=1}^{m} \frac{\omega_{i}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0} \\
& \quad+(x-\theta) \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(x)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0} .
\end{aligned}
$$

Since

$$
\omega(x)=\left(x-t_{i}\right) \cdot \omega_{i}(x)
$$

we have

$$
\omega^{\prime}(x)=\omega_{i}(x)+\left(x-t_{i}\right) \cdot \omega_{i}^{\prime}(x)
$$

whence

$$
\left(t_{i}-\xi\right) \cdot \omega_{i}^{\prime}(\xi)=\omega_{i}(\xi)
$$

Therefore,

$$
\begin{equation*}
q_{\xi}^{(m-1)}(\theta)=2 \cdot(-1)^{m-2}(\xi-\theta) \sum_{i=1}^{m} \frac{\omega_{i}^{\prime}(\xi)}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{0} . \tag{8.3}
\end{equation*}
$$

From this formula it is seen that on the interval $\left[t_{1}, t_{m}\right]$ the function $q_{\varepsilon}^{(m-1)}(\cdot)$ can change its sign only at the points $\xi$ and $\left\{t_{i}\right\}_{2}^{m-1}$, i.c.,

$$
\nu\left[q_{\epsilon}^{(m-1)}(\cdot)\right] \leq m-1
$$

However, by virtue of (8.2) the function $q_{q}(\cdot)$ has at least $2(m-1)$ zeroes counting multiplicity, i.e.,

$$
\nu\left[q_{\xi}(\cdot)\right] \geq 2(m-1)
$$

Hence, with the aid of Rolle's Theorem we conclude that

$$
\nu\left[q_{\xi}(\cdot)\right]=2(m-1)
$$

i.e., the function $q_{\xi}(\theta)=q(\xi, \theta)$ has no zeroes, different from (8.2), and, therefore, for each $\xi \in\left\{\tau_{j}\right\}_{1}^{m-1}$

$$
\operatorname{sign} q_{\xi}(\theta)=\operatorname{const}(\xi), \quad \theta \in\left(t_{1}, t_{m}\right)
$$

It remains to investigate the sign of this constant for $\xi=\tau_{j}$. By (8.2) for any $\theta \in\left(t_{1}, t_{n}\right)$

$$
\operatorname{sign} q_{\xi}(\theta)=\operatorname{sign} q_{\xi}\left(t_{m}-0\right)=(-1)^{m-1} \operatorname{sign} q_{\xi}^{(m-1)}\left(t_{m}-0\right)
$$

and by (8.3)

$$
\operatorname{sign} q_{\xi}^{(m-1)}\left(t_{m}-0\right)=(-1)^{m-1} \operatorname{sign} \omega_{m}^{\prime}(\xi) \operatorname{sign} \omega_{m}\left(t_{m}\right)
$$

Thus,

$$
\operatorname{sign} q_{\xi}(\theta)=\operatorname{sign} \omega_{m}^{\prime}(\xi)
$$

By Lemma 8

$$
\operatorname{sign} \omega_{m}^{\prime}(\xi)=\operatorname{sign} \omega_{\lrcorner}^{\prime \prime}(\xi)
$$

and it is evident that if

$$
\omega_{\lrcorner}^{\prime}(x)=m \prod_{j}\left(x-\tau_{j}\right), \quad \tau_{1}<\tau_{2}<\cdots<\tau_{m-1}
$$

then

$$
\operatorname{sign} \omega_{\mu}^{\prime \prime}\left(\tau_{j}\right)=(-1)^{m-1-j}
$$

Finally,

$$
\operatorname{sign} q_{\theta}\left(\tau_{j}\right)=\operatorname{sign} q_{\tau},(\theta)=(-1)^{m-1-j}, \quad \theta \in\left(t_{1}, t_{m}\right)
$$

and relations (8.1) and thus Lemma 9 are proved.

$$
\text { 9. The Case } k=m-1
$$

For the sake of completeness let us briefly reproduce from [6] the proof of Theorem 2 for the case $k=m-1$.

In this case, due to the definition (2.5)

$$
B_{m-1}(x, \theta)=(x-\theta)_{+}^{0}-\sum_{i=1}^{m} \frac{1}{\omega_{i}\left(t_{i}\right)}\left(t_{i}-\theta\right)_{+}^{m-1}
$$

Consider the classical B-spline $b(t)$ of degree $m-2$ with the breakpoints $\left\{t_{i}\right\}_{i=1}^{m}$

$$
\begin{equation*}
b(t)=(m-1) \sum_{i=1}^{m} \frac{\left(t_{i}-t\right)_{+}^{m-2}}{\omega_{د}^{\prime}\left(t_{i}\right)} \tag{9.1}
\end{equation*}
$$

which has the properties

$$
\operatorname{supp} b(\cdot)=\left(t_{1}, t_{m}\right), \quad b(\cdot) \geq 0, \quad \int_{t_{1}}^{t_{m \prime \prime}} b(t) d t=1
$$

It is seen that

$$
B_{m-1}(x, \theta)=\int_{-\infty}^{\theta}[b(t)-\delta(x-\theta)] d t=\int_{+\infty}^{\theta}[b(t)-\delta(x-\theta)] d t
$$

where $\delta$ is the Dirac function.
Thus, the kernel $B_{m-1}(x, \theta)$ as a function with respect to $\theta$ changes its sign at the point

$$
\theta_{x}=x, \quad x \in J_{m, k}(\Delta)=\left(t_{1}, t_{m}\right)
$$

and for the value of the pointwise deviation $L_{m, m-1}(\Delta, x)$, we obtain by Lemma D and Eq. (2.2) the following expression

$$
\begin{align*}
L_{m, m-1}(\Delta, x) & =\left|S_{m-1}\left(x, \theta_{x}\right)\right|=\left|S_{m-1}(x, x)\right| \\
& =-S_{m-1}(x, x)=\frac{1}{m} \sum_{i=1}^{m} \frac{\left(t_{i}-x\right)_{ \pm}^{m}}{\omega_{i}\left(t_{i}\right)}, \tag{9.2}
\end{align*}
$$

where as before $z_{ \pm}^{m}=z^{m} \cdot \operatorname{sign} z$.

With the aid of (9.1), (9.2) it can be readily verified that

$$
L_{m, m-1}(\Delta, x)=\int_{t_{1}}^{x} \int_{t_{1}}^{\theta} b(t) d t d \theta+\int_{t_{m}}^{x} \int_{t_{m}}^{\theta} b(t) d t d \theta
$$

and thus

$$
L_{m, m-1}^{\prime \prime}(\Delta, x)=2 b(x) \geq 0
$$

which completes the proof.
Remark. The case $k=m-1$ of Theorem 2 given in Section 9 is also contained in the recent paper by G. Howell [J. Approx. Theory 67 (1991), 164-173].

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